

Computational Methods for Macroeconomics (Part II)

Lecture 4: Heterogeneous firm models

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Background: Heterogeneous firm models

- ▶ Prescott and Kydland (1982): Time-to-build for capital investment
- ▶ Hopenhayn (1992): stationary equilibrium distribution of firm-level allocations: entry, exit, and size.
- ▶ Capital adjustment cost
 - Abel (1983): Convex capital adjustment cost
 - Cooper and Haltiwanger (2006): “The Nature of Capital Adjustment Costs”
- ▶ Lumpy investment
 - Caballero and Bertola (1994), Caballero and Engel (1999), Abel and Eberly (2002)
 - Khan and Thomas (2008), Khan and Thomas (2003): Strong GE effect
 - Bachmann et al. (2013), Winberry (2021), Koby and Wolf (2020), Lee (2022): Weak GE effect
- ▶ Heavy tail distribution
 - Gabaix (2009): A heavy-tail of the firm size distribution
- ▶ Financial friction
 - Bernanke and Gertler (1989), Kiyotaki Moore (1997), Brunnermeier and Sannikov (2014)

Background: Khan and Thomas (2008)

- ▶ Khan and Thomas (2008) studies heterogeneous establishments (c.f., firms) under the aggregate productivity fluctuations.
- ▶ An improved investment-to-capital distribution compared to Khan and Thomas (2003).
- ▶ Establishment-level nonlinear investment dynamics: (S, s) cycle.
- ▶ Macro-level log-linear investment dynamics: strong general equilibrium effect.
- ▶ Basic ingredients:
 - Heterogeneous idiosyncratic productivity process under the incomplete market (time-to-build).
 - Aggregate TFP fluctuations (Krusell and Smith, 1997).
 - The fixed cost, $\xi \sim_{iid} Unif[0, \bar{\xi}]$: smoothing the kink of the value function.
 - A small-scale investment is allowed, which is not subject to a fixed cost.
 - Value function normalization steps.
 - Non-trivial market clearing condition.
 - Representative household and competitive factor market.

Model

Establishment-level production

- ▶ At the beginning of period t , a firm i is given with $(k_{it}, z_{it}; S_t)$:
 - k_{it} : Pre-determined establishment-level capital stock.
 - z_{it} : Establishment-level idiosyncratic productivity (AR(1) process).
 - $S_t = \{A_t, \Phi_t\}$: A_t is aggregate productivity (AR(1) process); Φ_t is the distribution of individual establishments.
- ▶ Cobb-Douglas production function with DRS ($\alpha + \gamma < 1$) where labor demand is contemporaneously determined:

$$f(k_{it}, z_{it}; S_t) = A_t z_{it} (k_{it})^\alpha n_{it}^\gamma$$

- ▶ Operating profit due to DRS: $\pi(k_{it}, z_{it}; S_t) = \max_{n_{it}} f(k_{it}, z_{it}; S_t) - w_t n_{it}$
- ▶ Operating profit = Dividends (D_{it}) + Investment (I_{it})
- ▶ The objective function is maximizing the firm value:

$$J_{it} = \max_{\{D_{it}\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \frac{1}{R_t} D_{it}$$

Establishment-level investment

- ▶ A firm needs to decide k_{it+1} by choosing I_{it} .

$$k_{it+1} = (1 - \delta)k_{it} + I_{it}$$

- ▶ Two options in the investment scale: large/small
- ▶ If $I_{it} \in \Omega(k_{it}) := [\nu k_{it}, \nu k_{it}]$, then there is no fixed cost. ($\nu < \delta$)
- ▶ If $I_{it} \notin \Omega(k_{it}) := [\nu k_{it}, \nu k_{it}]$, then a fixed cost $\xi_{it} \sim_{iid} Unif([0, \bar{\xi}])$: Why?
- ▶ Role of fixed adjustment cost:
 - Inaction period: no lumpy investment - inside the (S, s) cycle.
 - Large adjustment: Jumping from s to S .
- ▶ No convex adjustment cost in Khan and Thomas (2008) but Winberry (2021) introduces a convex adjustment cost.
- ▶ Role of convex adjustment cost:
 - When your productivity jumps from 1 to 1.5, the unconstrained optimal level of future capital jumps identically across the different size of firms.
 - Without the convex adjustment cost, the capital stock of small firms can immediately jump up to the optimal level, being a sudden large firm.

Household

A representative household consumes, **supplies labor**, and saves.

$$\begin{aligned} V(a; S) &= \max_{c, a', l_H} \log(c) - \eta l_H + \beta \mathbb{E} V(a'; S') \\ \text{s.t. } c + \int \Gamma_{S, S'} q(S, S') a(S') dS' &= w(S) l_H + \int a(S) dS \\ G_\phi(S) &= \Phi', \quad G_A(A) = A', \quad S = \{\Phi, A\} \end{aligned}$$

- ▶ a : an equity portfolio, Φ : distribution of firms
 A : aggregate productivity, c : consumption
 a' : a state-contingent future saving portfolio, l_H : labor supply (indivisible)
 q : state-contingent bond price, w : wage
- ▶ Household is holding the equity of firms as their wealth.
- ▶ Stochastic discount factor:

$$q(S, S') = \beta \frac{C(S)}{C(S')}$$

Khan and Thomas (2008) defines $p(S) := \frac{1}{C(S)}$, which will be extensively used after the normalization.

Recursive formulation

$$J(k, z; S) = \pi(k, z; S) + (1 - \delta)k + \int_0^{\bar{\xi}} \max \{R^*(k, z; S) - w(S)\xi, R^c(k, z; S)\} dG_{\xi}(\xi)$$

$$R^*(k, z; S) = \max_{k'} -k' - c(k, k') + \mathbb{E}m(S, S')J(k', z'; S')$$

$$R^c(k, z; S) = \max_{k^c - (1-\delta)k \in \Omega(k)} -k^c - c(k, k^c) + \mathbb{E}m(S, S')J(k^c, z'; S')$$

(Operating profit) $\pi(z, k; S) := \max_{n_d} zAk^{\alpha}n_d^{\gamma} - w(S)n_d$ (n_d : labor demand)

(Constrained investment) $I^c \in \Omega(k) := [-k\nu, k\nu]$ ($\nu < \delta$)

(Convex adjustment cost) $c(k, k') := \left(\mu'/2\right) \left((k' - (1 - \delta)k)/k\right)^2 k$

(Khan and Thomas (2008): $\mu = 0$)

(Idiosyncratic productivity) $z' = G_z(z)$ (AR(1) process)

(Stochastic discount factor) $m(S, S') = \beta (C(S)/C(S'))$

(Aggregate states) $S = \{A, \Phi\}$

(Aggregate law of motion) $\Phi' := H(S), A' = G_A(A)$ (AR(1) process),

National accounting

- ▶ National account tracking is important for the efficient GE computation.

$$Y = C + I = C + (\tilde{I} + Adj.Cost)$$

$$C = Y - I$$

$$= (\Pi + W * L) - I$$

$$= (\Pi - I) + W * L$$

$$= \underbrace{D}_{\text{Dividend income}} + \underbrace{W * L}_{\text{Labor income}}$$

- ▶ Therefore, consumption is total dividends plus total labor expenses.
- ▶ After obtaining the distribution of firms, we compute total dividend and labor expense. Then, we obtain the consumption.
- ▶ Why does consumption matter? It determines $w(S)$ and $q(S, S')$: next slide.

Non-trivial market clearing condition

- ▶ From the intra-temporal labor supply optimality condition:

$$\begin{aligned}\eta &= \lambda(\mu(S); S)w(S) \\ &= p(S)w(S)\end{aligned}$$

- ▶ Therefore, if $p(S)$ is known, then $w(S)$ is determined. (What if GHH utility?)
- ▶ We still need to know SDF, $q(S, S')$, to solve the problem.
- ▶ However, the following slide's normalization eases the problem: $p(S)$ is the only price!
- ▶ Where is $p(S)$ is determined?
 - There is no closed-form to determine $P(S)$.
 - The notorious internal loop:
 1. Guess $p(S)$.
 2. Using the given distribution, $\Phi(S)$ compute the aggregate consumption $c(S) = D(S) + W(S) * L(S)$.
 3. Compute $p^{update}(S) = 1/c(S)$, and repeat the steps until $\|p(S) - p^{update}(S)\| < tol$

Normalization

Multiply $p(S) = 1/C(S)$ on the both sides of the value function identity.

$$p(S)J(k, z; S) = p(S)(\pi(k, z; S) + (1 - \delta)k) + \int_0^{\bar{\xi}} \max \{p(S)R^*(k, z; S) - p(S)w(S)\xi, p(S)R^c(k, z; S)\} dG_{\xi}(\xi)$$

Define $(\tilde{J}, \tilde{R}^*, \tilde{R}^c)$ as follows:

$$\tilde{J}(k, z; S) := p(S)J(k, z; S)$$

$$\begin{aligned} \tilde{R}^*(k, z; S) &:= p(S)R^*(k, z; S) &= \max_{k'} (-k' - c(k, k'))p(S) + \mathbb{E}p(S)q(S, S')J(k', z'; S') \\ & &= \max_{k'} (-k' - c(k, k'))p(S) + \mathbb{E}\beta p(S')J(k', z'; S') \\ & &= \max_{k'} (-k' - c(k, k'))p(S) + \mathbb{E}\beta \tilde{J}(k', z'; S') \end{aligned}$$

$$\tilde{R}^c(k, z; S) := p(S)R^c(k, z; S) = \max_{k^c - (1 - \delta)k \in \Omega(k)} (-k^c - c(k, k^c))p(S) + \mathbb{E}\beta \tilde{J}(k^c, z'; S')$$

It is necessary to check whether the recursive form is preserved for the normalized value functions.

$$\tilde{J}(k, z; S) = p(S)(\pi(k, z; S) + (1 - \delta)k) + \int_0^{\bar{\xi}} \max \{ \tilde{R}^*(k, z; S) - P(S)w(S)\xi, \tilde{R}^c(k, z; S) \} dG_{\xi}(\xi)$$

► Thanks to this normalization, we only need to track $p(S)$ instead of $q(S, S')$.

Smoothing the kink and the extensive margin

$$\int_0^{\bar{\xi}} \max \{R^*(k, z; S) - w(S)\xi, R^c(k, z; S)\} dG_{\xi}(\xi) \quad (1)$$

Then, there exists $\xi^*(k, z; S)$ such that

$$R^*(k, z; S) - w(S)\xi > R^c(k, z; S) \quad \text{if } \xi < \xi^*(k, z; S)$$

$$R^*(k, z; S) - w(S)\xi \leq R^c(k, z; S) \quad \text{if } \xi \geq \xi^*(k, z; S)$$

Especially, $\xi^*(k, z; S) = \frac{R^*(k, z; S) - R^c(k, z; S)}{w(S)}$ is the closed-form characterization.

- ▶ In the support of ξ , $[0, \xi^*)$ corresponds to large-scale investment and $[\xi^*, \bar{\xi}]$ corresponds to small-scale investment: define $\psi(k, z; S) := \frac{\min\{\xi^*(k, z; S), \bar{\xi}\}}{\bar{\xi}}$
- ▶ With probability $\psi(k, z; S)$, a firm makes a large-scale investment.
- ▶ Eq (1) becomes a linear combination form: No Kink! (c.f., Discrete choice model)

$$\psi(k, z; S) \left(R^*(k, z; S) - w(S) \frac{\xi^*(k, z; S)}{2} \right) + (1 - \psi(k, z; S)) (R^c(k, z; S)).$$

Recursive competitive equilibrium

$(g_c, g_a, g_{IH}, g_{k^*}, g_{k^c}, g_{\xi^*}, g_{n_d}, \tilde{V}, \tilde{J}, \tilde{R}^*, \tilde{R}^c, p, w)$ is a recursive competitive equilibrium if the following conditions are satisfied.

1. $g_c, g_{IH}, \tilde{V}$ and g_a , solves the household's problem.
2. $g_{k^*}, g_{k^c}, g_{\xi^*}, g_{n_d}, \tilde{J}, \tilde{R}^*$, and $\tilde{R}^c$ solve a firm's problem.
3. Market Clearing:

$$\text{(Labor Market)} \quad g_{IH}(\Phi; S) = \int \left(g_{n_d}(k, z; S) + \left(\frac{g_{\xi^*}(k, z; S)}{\bar{\xi}} \right) \left(\frac{g_{\xi^*}(k, z; S)}{2} \right) k^\zeta \right) d\Phi$$

$$\begin{aligned} \text{(Product Market)} \quad g_c(\Phi; S) = & \int \left(z A k^\alpha g_{n_d}(k, z; S)^\gamma \right. \\ & - \left((g_{k^*}(k, z; S) - (1 - \delta)k) + c(k, g_{k^*}(k, z; S)) \right) \frac{g_{\xi^*}(k, z; S)}{\bar{\xi}} \\ & \left. - \left((g_{k^c}(k, z; S) - (1 - \delta)k) + c(k, g_{k^c}(k, z; S)) \right) \frac{1 - g_{\xi^*}(k, z; S)}{\bar{\xi}} \right) d\Phi \end{aligned}$$

4. Consistency Condition: [▶ Detail](#)

Computation

Roadmap

- ▶ The following is the roadmap for computation section.
 1. Set the parametric law of motion: **assumption**
 2. Guess the parameters: $\#(S) \times 2 \times 2$
 3. Solution (optimization)
 - ▶ VFI/PFI/EGM/Projection method
 - ▶ Interpolation
 4. Simulation and **internal loop for price p**
 - ▶ Simulation
 - ▶ Aggregation
 - ▶ Update p until convergence
 5. Update the parameters
 6. **After convergence, verify the assumption**
- ▶ After this, we will talk about more recent developments.

Basic setup

The basic steps.

- ▶ Set directories
- ▶ Set parameters (might be a function argument)

Then, two important steps follow.

- ▶ Setting grid points.
 - Individual capital grid
 - Aggregate capital grid: this grid can be sparse (5~10 grids)
- ▶ Discretizing idiosyncratic shock process (Markov chain)
 - Tauchen method
 - Rouwenhorst method

Parametric law of motion

There are two layers of choices:

- ▶ First, we need to set what are **sufficient statistics** to characterize the dynamics of the individual state distribution.
 - A good candidate is the first moment of the endogenous individual state.
 - As in Krusell and Smith (1998), by tracking only K_t , the aggregate prices are also characterized (Median also works well).
- ▶ Then, we need to decide the **parametric form** of the law of motion.
- ▶ So start from the following parameter guesses $(\alpha_S^K, \beta_S^K; \alpha_S^P, \beta_S^P)$

$$\log(K_{t+1}) = \alpha_S^K + \beta_S^K \log(K_t) \quad \text{when } S_t = S$$

$$\log(p_t) = \alpha_S^P + \beta_S^P \log(K_t) \quad \text{when } S_t = S$$

- ▶ K_t does not immediately give p_t (no closed-form). But it should give some inference on p_t !

Computation - GE: Solution

Value function iteration with accelerator

Now we know $p(S)$, if we are given with K . The pseudo code is as follows:

1. Guess $J^{(n)} : \mathcal{K} \times \mathcal{Z} \times \mathcal{A} \times \mathcal{K}^{Agg} \rightarrow \mathbb{R}$
2. Solve for the policy function, $g_k^{(n)}$ (using monotonicity: $g_k^{(n)} \geq g_{\tilde{k}}^{(n)}$ for $k \geq \tilde{k}$).
 - We have K , so we know (p, K') from the law of motion.
 - Interpolate the value functions over K' to have $J^{(n)}(\cdot, z'; A', K')$
 - Then, the problem becomes a typical VFI.
3. Update $J^{(n+1)}$ using the policy function, $g_k^{(n)}$.
4. Update $J^{(n+2)}$ using the policy function, $g_k^{(n)}$.
- ...
5. Update $J^{(n+m)}$ using the policy function, $g_k^{(n)}$.
6. Check if $\|J^{(n+m)} - J^{(n+m-1)}\|_p < Tol$
 - If yes, the solution converged.
 - If no, go back to step 1.

Computation - GE: Simulation

Non-trivial market clearing condition (Revisited)

We use a non-stochastic iteration method. (Eigenvalue method is not feasible).

- ▶ Simulate a long enough aggregate shock path using Γ_S . (Not idiosyncratic shocks)
- ▶ Start from an initial guess $\mathcal{H}_0$. Compute the corresponding K_0 . And then internal loop.
 - Guess p_0 , and solve the problem to get g_{d0} and g_{l0} .
 - Compute c_0 using $(\mathcal{H}_0, g_{d0}, g_{l0}, w_0)$.
 - Compute $p_0^{update} = 1/c_0$, and repeat the steps until $\|p_0 - p_0^{update}\| < tol$.
 - So, we have $(K_0, p_0^{converged})$.
- ▶ Let $\mathcal{H}_0$ evolve to $\mathcal{H}_1$ using $g_{a0}^{converged}$, and compute the corresponding K_1 .
 - Guess p_1 , and solve the problem to get g_{d1} and g_{l1} .
 - Compute c_1 using $(\mathcal{H}_1, g_{d1}, g_{l1}, w_1)$.
 - Compute $p_1^{update} = 1/c_1$, and repeat the steps until $\|p_1 - p_1^{update}\| < tol$.
 - So, we have $(K_1, p_1^{converged})$.
- ▶ ...
- ▶ By repeating this process, we obtain $\{K_t, p_t^{converged}\}_{t=0}^T$.
- ▶ Discard the the burn-in period to get $\{K_t, p_t^{converged}\}_{t=burnIn}^T$.

Updating the parameters

- ▶ We have $\{K_t, p_t^{\text{converged}}\}_{t=\text{burnIn}}^T$ and $\{S_t\}_{t=\text{burnIn}}^T$.
- ▶ Fit the time-series into the parametric form of the law of motion to estimate the parameters: $(\alpha_S^K, \beta_S^K; \alpha_S^P, \beta_S^P)$

$$\begin{aligned} \log(K_{t+1}) &= \alpha_S^K + \beta_S^K \log(K_t) & \text{when } S_t = S \\ \log(p_t^{\text{converged}}) &= \alpha_S^P + \beta_S^P \log(K_t) & \text{when } S_t = S \end{aligned}$$

- ▶ If the parameter estimates are not close to the guess, return to the initial step.
- ▶ Otherwise, the solution is converged.
- ▶ Check R^2 as the first check for the validity of the parametric form.

Close-to-perfect aggregation

TABLE A.II
FORECASTING RULES IN FULL LUMPY MODEL

Productivity ^a	β_0	β_1	S.E.	Adj. R^2
A. Forecasting m'_1				
z_1 (119 obs)	0.009	0.800	0.15e-3	1.0000
z_2 (298 obs)	0.016	0.798	0.22e-3	0.9999
z_3 (734 obs)	0.023	0.796	0.23e-3	0.9999
z_4 (1,208 obs)	0.030	0.795	0.26e-3	0.9999
z_5 (1,682 obs)	0.037	0.794	0.27e-3	0.9999
z_6 (1,871 obs)	0.044	0.799	0.28e-3	0.9999
z_7 (1,706 obs)	0.051	0.793	0.26e-3	0.9999
z_8 (1,237 obs)	0.058	0.792	0.24e-3	0.9999
z_9 (751 obs)	0.065	0.792	0.23e-3	0.9999
z_{10} (295 obs)	0.072	0.791	0.25e-3	0.9999
z_{11} (99 obs)	0.079	0.791	0.19e-3	0.9999
B. Forecasting p				
z_1 (119 obs)	0.994	-0.397	0.03e-3	1.0000
z_2 (298 obs)	0.986	-0.395	0.04e-3	1.0000
z_3 (734 obs)	0.977	-0.394	0.04e-3	1.0000
z_4 (1,208 obs)	0.968	-0.393	0.05e-3	1.0000
z_5 (1,682 obs)	0.958	-0.392	0.05e-3	1.0000
z_6 (1,871 obs)	0.949	-0.391	0.05e-3	1.0000
z_7 (1,706 obs)	0.940	-0.389	0.05e-3	1.0000
z_8 (1,237 obs)	0.931	-0.388	0.05e-3	1.0000
z_9 (751 obs)	0.921	-0.386	0.04e-3	1.0000
z_{10} (295 obs)	0.912	-0.384	0.05e-3	1.0000
z_{11} (99 obs)	0.903	-0.382	0.04e-3	1.0000

^aForecasting rules are conditional on current aggregate total factor productivity z_i . Each regression takes the form $\log(y) = \beta_0 + \beta_1 \log(m_1)$, where $y = m'_1$ or p .

Notes: The table is from Khan and Thomas (2008).

Concluding remarks

Summary

- ▶ Khan and Thomas (2008) provides a great benchmark to start with.
 - The micro-level non-linearity washes out if the general equilibrium effect is strong enough.
 - Strength of the general equilibrium effect depends on the price-elasticities of agents.
 - Are the price-elasticities at an empirically-supported range?
- ▶ The normalization technique is a great idea: See Winberry (2021) and Lee (2022).
- ▶ Thanks to the close-to-perfect aggregation, the algorithm of Krusell and Smith (1997) perfectly works.
 - The log-linear law of motion of sufficient statistics perfectly governs the aggregate dynamics.
 - No closed-form for $p(S)$: the internal loop is needed at a computational cost.
- ▶ What about financial frictions?
 - Consult with Ferreira, Haber, and Rörig (2021).
 - Real friction vs. Financial friction

Recursive competitive equilibrium: consistency condition [▶ Back](#)

(Consistency) $G_\Phi(\Phi) = H(\Phi) = \Phi'$, where for $\forall K' \subseteq \mathbb{K}$ and $z' \in \mathbb{Z}$,

$$\begin{aligned} \Phi'(K', z') = \int \Gamma_{z, z'} \left(\mathbb{I}\{g_{k^*}(k, z; S) \in K'\} \frac{g_{\xi^*}(k, z; S)}{\bar{\xi}} \right. \\ \left. + \mathbb{I}\{g_{k^c}(k, z; S) \in K'\} \frac{1 - g_{\xi^*}(k, z; S)}{\bar{\xi}} \right) d\Phi \end{aligned}$$